



# OPERA

## Observational Products for End-Users from Remote Sensing Analysis

### Deploying Corner Reflectors for Geolocation Accuracy Assessment and Displacement Monitoring: From experiment formulation to product validation and analysis of OPERA CSLC and DISP products

November 2024

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# OPERA Enabling End-Users to Take Action

## Observation Products for End-users from Remote sensing Analysis



- **Free and open Analysis Ready Data** products designed for science and application stakeholders.
- 5 product lines in production
- ***New since last science highlights:***
  - ***Sentinel-1 (radar) Surface Water product in production.***
  - ***OPERA funded for creation of a Vertical Land Motion Product***
  - ***RTC-S1 product is CEOS ARD approved***

**OPERA is spearheading an innovative model within NASA that goes beyond a single mission (Landsat 8/9, Sentinel-1/2, NISAR) to develop multiple product lines**

# Product Details

**Latency:** As soon as the input data is available  
**Posting:** 30m or better  
**Temporal Sampling:** sub-weekly to weekly



## Level-2 products



- **Description:** S1 radar backscatter corrected for the topography. Basis for the DSX-S1 and DIST-S1 products.
- **Coverage:** Near-global
- **Spatial Resolution:** 30 m
- **Product Record Begins:** Oct. 2023

Available now!



- **Description:** Geocoded and coreg. SLC (S1, NISAR). Basis for all the DISP products.
- **Coverage:** North America\*
- **Spatial Resolution:** ≤ 10 m
- **Product Record Begins:** Apr. 2014 (S1) and TBD (NISAR)
- **Production Begins:** Oct. 2023 (S1), TBD (NISAR)

Available now!

[www.jpl.nasa.gov/go/opera](http://www.jpl.nasa.gov/go/opera)  
[www.nasa.gov](http://www.nasa.gov)

## Level-3 products



- **Description:** Maps surface water using optical (HLS) and SAR imagery (S1, NISAR)
- **Coverage:** Near-global
- **Temporal resolution:** every few days
- **Spatial Resolution:** 30 m
- **Product Record Begins:** Apr. 2023 (HLS), Sep. 2024 (S1), Jun. 2026 (NISAR)

Available now!



- **Description:** Maps vegetation disturbance using optical (HLS) and SAR imagery (S1)
- **Coverage:** Near-global
- **Temporal resolution:** every few days
- **Spatial Resolution:** 30 m
- **Product Record Begins:** Feb. 2023 (HLS), Mar. 2026 (S1)

Available now!



- **Description:** Maps surface displacements in LOS (S1 and NISAR)
- **Coverage:** North America\*
- **Temporal resolution:** 6, 12, or 24 days
- **Spatial Resolution:** ≤ 30 m
- **Product Record Begins:** Apr. 2014 (S1), NISAR validated record.
- **Production Begins:** Dec. 2024 (S1) Sep. 2026 (NISAR)

Available End of 2024!

## Level-4 products



- **Description:** Maps surface displacements in vertical + horiz. (S1 and NISAR)
- **Coverage:** North America\*
- **Temporal resolution:** 6, 12, or 24 days
- **Spatial Resolution:** ≤ 100 m
- **Product Record Begins:** Jan. 2019 (S1), NISAR validated record.
- **Production Begins:** Apr. 2028 (S1 + NISAR)

Available in 2028!

OPERA data is available through SNWG data portal:

<https://search.earthdata.nasa.gov/search?portal=snwg>

OPERA code in open source domain is built on core ISCE3 modules developed by NISAR.

<https://www.jpl.nasa.gov/go/opera/resources/opera-code-repositories-and-resources/>

# Project Requirements



## CSLC-S1

Absolute Location Error  
(ALE)

*The Sentinel-1-based CSLC product (CSLC-S1) shall have an Absolute Location Error **1.5 meters or better in both the ground range and azimuth directions**, excluding the effects of DEM errors and ionospheric scintillation on SAR acquisitions, in **at least 80% of all validation products considered**.*

## CSLC-S1

Relative Location Error  
(RLE)

*The Sentinel-1-based CSLC product (CSLC-S1) shall have a Relative Location Error of **0.5 meters and 0.75 meters or better in ground range and azimuth directions** respectively, in areas with high cross-correlation accuracy, excluding the effects of DEM errors and ionospheric scintillation on SAR acquisitions, in **at least 80% of all validation products considered**. The product's Relative Location Error shall be determined relative to a single reference image within the stack.*

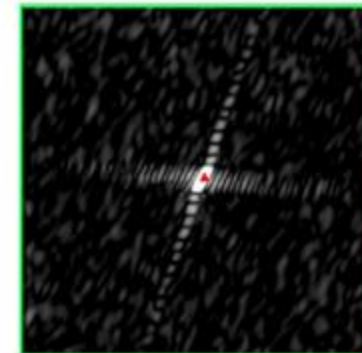
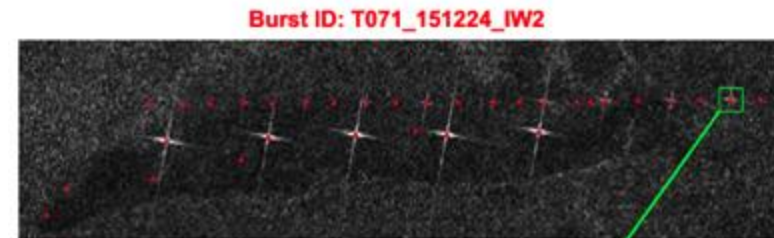
## DISP-S1

Sentinel-1 DISP product (DISP-S1) shall measure from a single line-of-sight geometry surface displacement rates with an uncertainty of **5 mm per yr or better over length scales within  $0.1 \text{ km} < L < 50 \text{ km}$  from 4 years of regularly sampled** (at least 80% of Sentinel-1 acquisitions at 12 days sampling or better) **Sentinel-1 A/B data** (VV polarization imagery in IW-mode), in regions where the interferometric signal is maintained (i.e., the coherence is above 0.5).

# Using corner reflectors to assess product requirement



To validate the **Absolute Location Error (ALE) of OPERA CSLCs**, we mainly use corner reflectors over Rosamond, California, Alaska (Fairbanks), and Oklahoma. ALE is evaluated through point-target analysis.



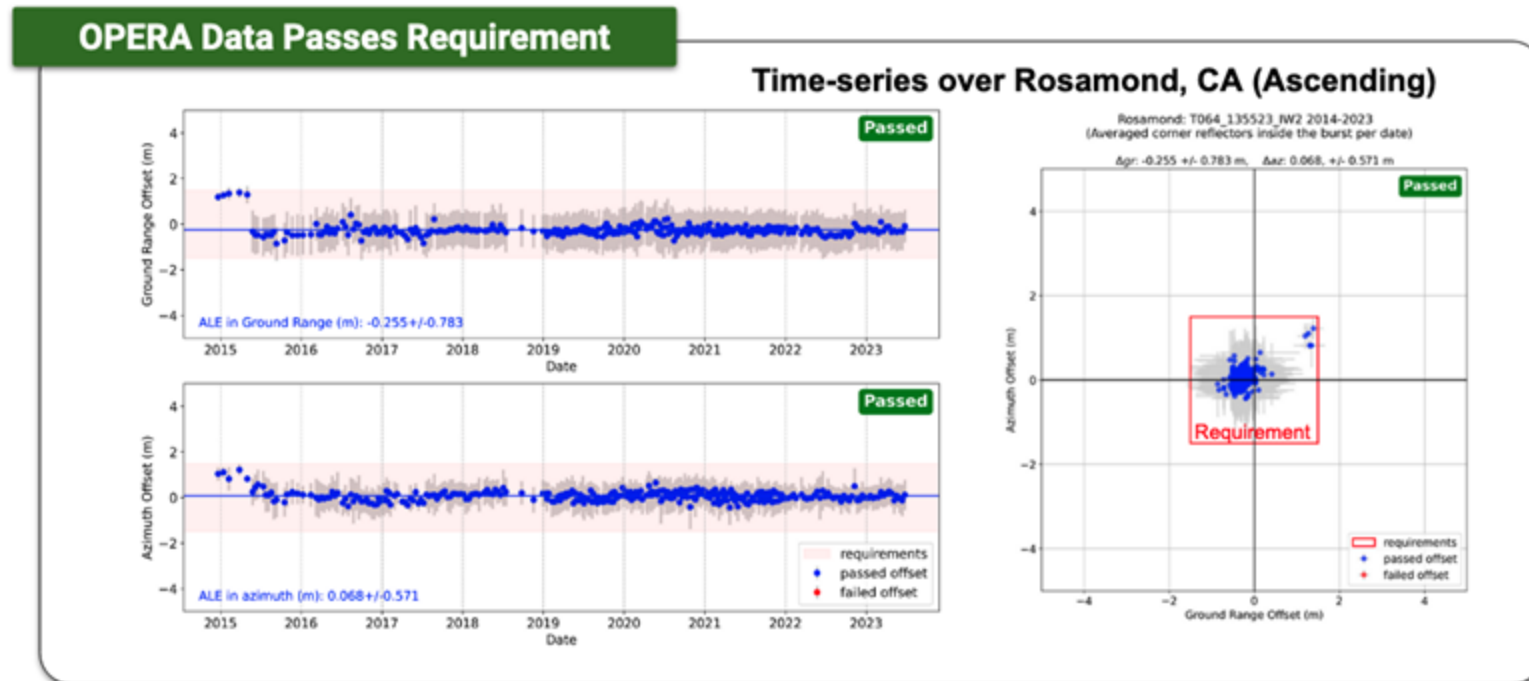
30x30m ground projected SLC

Oversampled 32 x 32 patch centered on a CR

# Prior to release: OPERA CSLC-S1 meets all L2 requirements



	L2 Accuracy Requirements	CSLC-S1
<b>ALE</b>	<b>1.5 m</b> in Ground Range and Azimuth for <b>80%</b> of validation data	<b>100%</b> of validation data met requirement
<b>RLE</b>	<b>0.5 m</b> in Ground Range and <b>0.75 m</b> in Azimuth for <b>80%</b> of validation data	<b>88%</b> of validation data met requirement

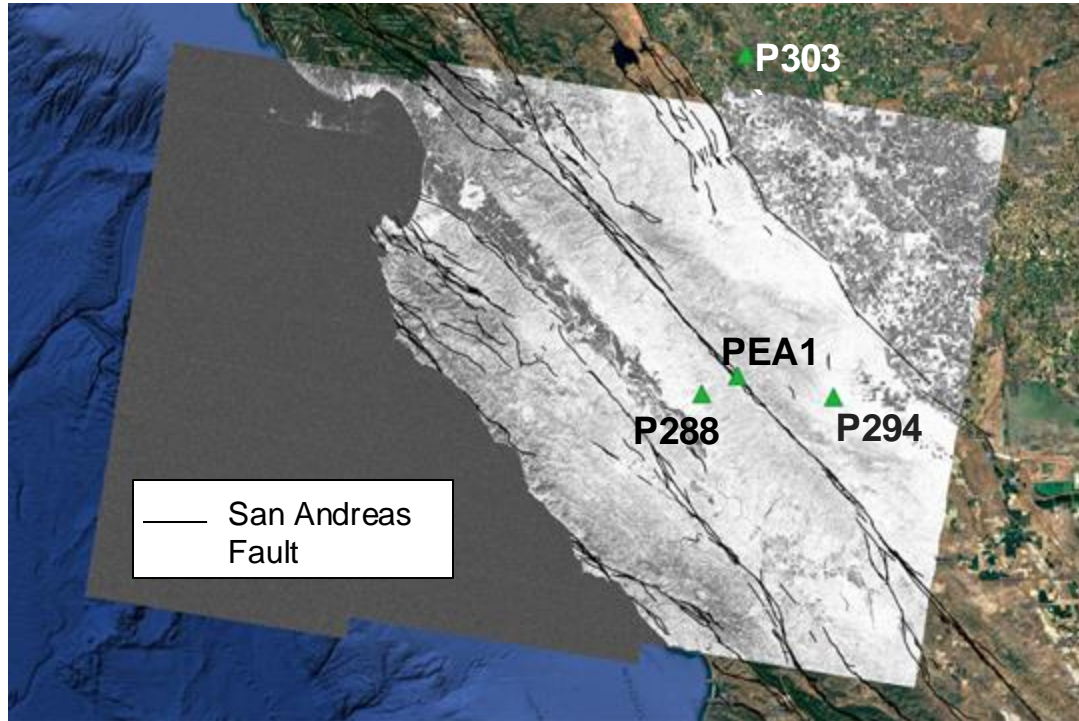


← Example evaluation of ALE for an Ascending track CSLC-S1 product over Rosamond, CA

# Deploying corner reflectors across San Andreas Fault and in Central Valley:

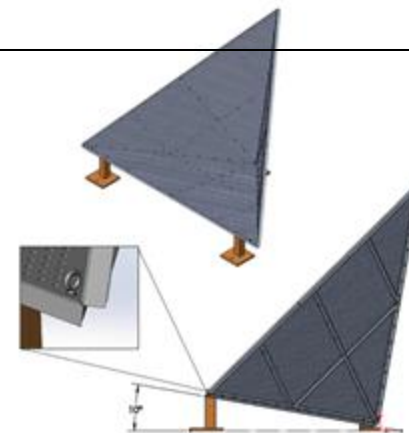
*An experiment to support OPERA's CalVal and Algorithm Development*

National Aeronautics and  
Space Administration



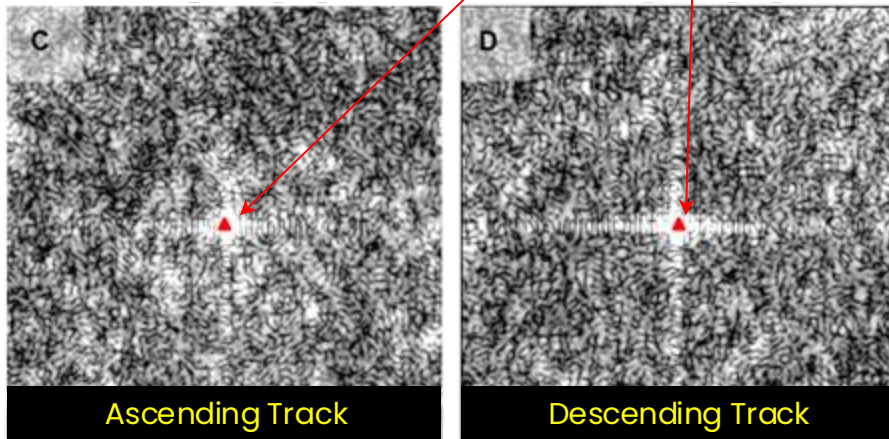
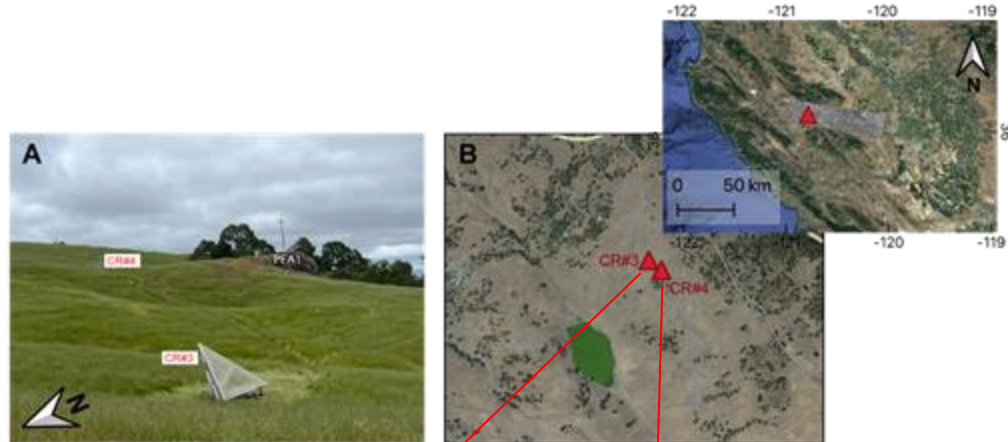
OPERA corner reflectors (▲ deployed), collocated with EarthScope-managed Continuous GNSS stations across the creeping segment of the San Andreas Fault and in Central Valley, CA. Underlying image is the phase correlation layer from OPERA DISP-S1 product.

- San Andreas Fault (SAF) is moving at a rate of ~36 mm/yr (Ludwig et al, 2019) whereas Central Valley in California is subsiding at a rate of > 200 mm/yr (Govorcin et al., in review).
- Displacement product from InSAR can suffer from unwrapping errors.
- Corner reflectors support the OPERA CalVal and algorithm development activities for CSLC and DISP products (Sentinel-1 and NISAR).
  - 6 x 2.4m reflectors across SAF (P288, PEA1, P294)
  - 1 x 2.4m reflector and 1 x 1.2m reflector are deployed in Central Valley (P303)



←Design of the OPERA 2.4-m corner reflectors (perforated aluminum)  
Credit: L. Ortiz

# Rain or shine deployment in partnership with Earthscope



OPERA Corner Reflector Team: M. Grace Bato, Bruce Chapman, Annemarie Peacock, Simran Sangha, and the EarthScope team (Andre Basset, Matt Burgess, James Downing, Karl Feaux, Bill Funderburk, Shawn Lawrence, Doerte Mann, Glenn Mattioli).



# On going DISP-S1 product validation activities



## Passes Requirement

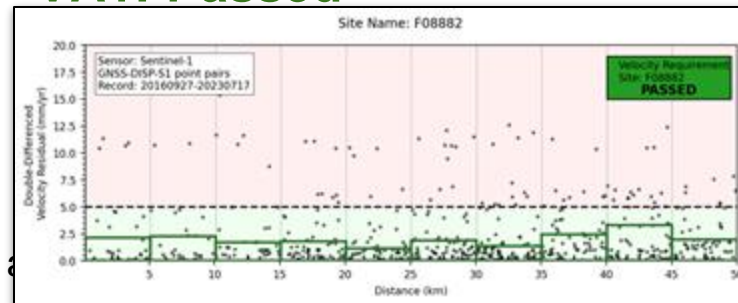
### Example: Houston, USA, Frame 08882 (DISP-S1)

**VA1:** Direct comparison of GNSS and InSAR over regions with dense GNSS networks.

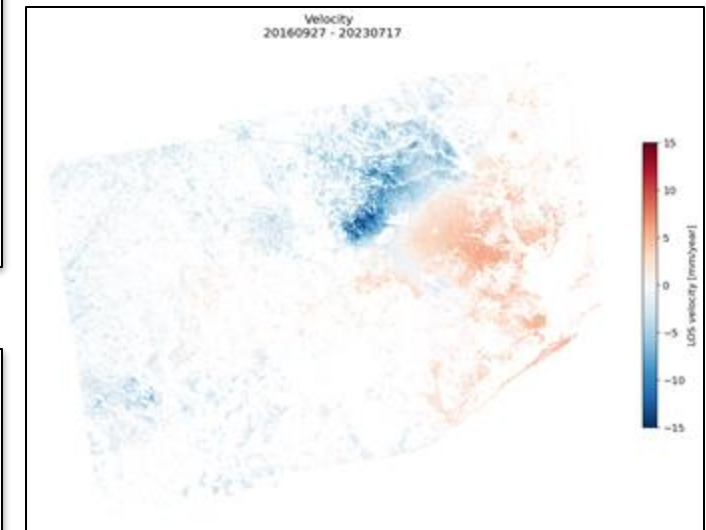
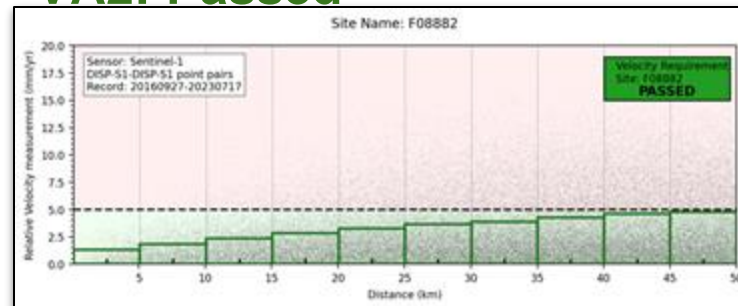
**VA2:** InSAR residual analysis.

**VA3:** (*Experimental*): Direct comparison of the OPERA Corner Reflectors installed across the San Andreas Fault and InSAR.

#### VA1: Passed



#### VA2: Passed



# On going DISP-S1 product validation activities

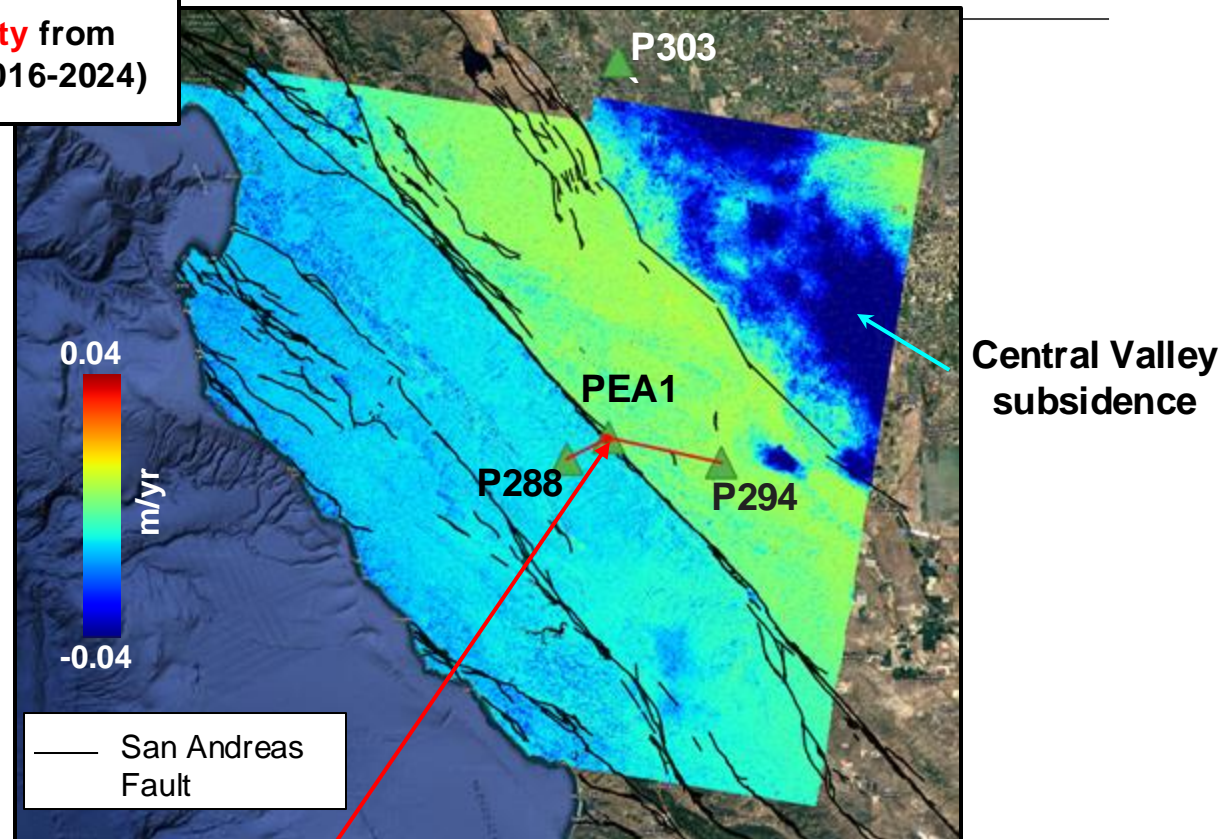


Derived **velocity** from  
DISP-S1 data (2016-2024)

**VA1:** Direct comparison of  
GNSS and InSAR over regions  
with dense GNSS networks.

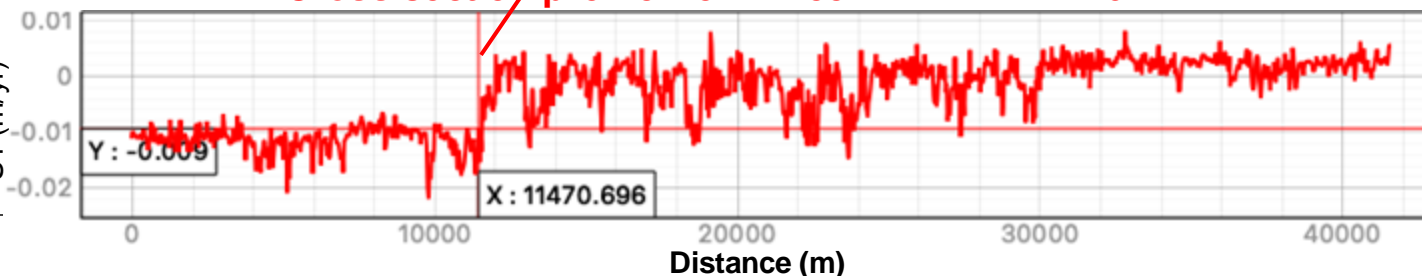
**VA2:** InSAR residual analysis.

**VA3:** (*Experimental*): Direct  
comparison of the OPERA  
Corner Reflectors installed  
across the San Andreas Fault  
and InSAR.



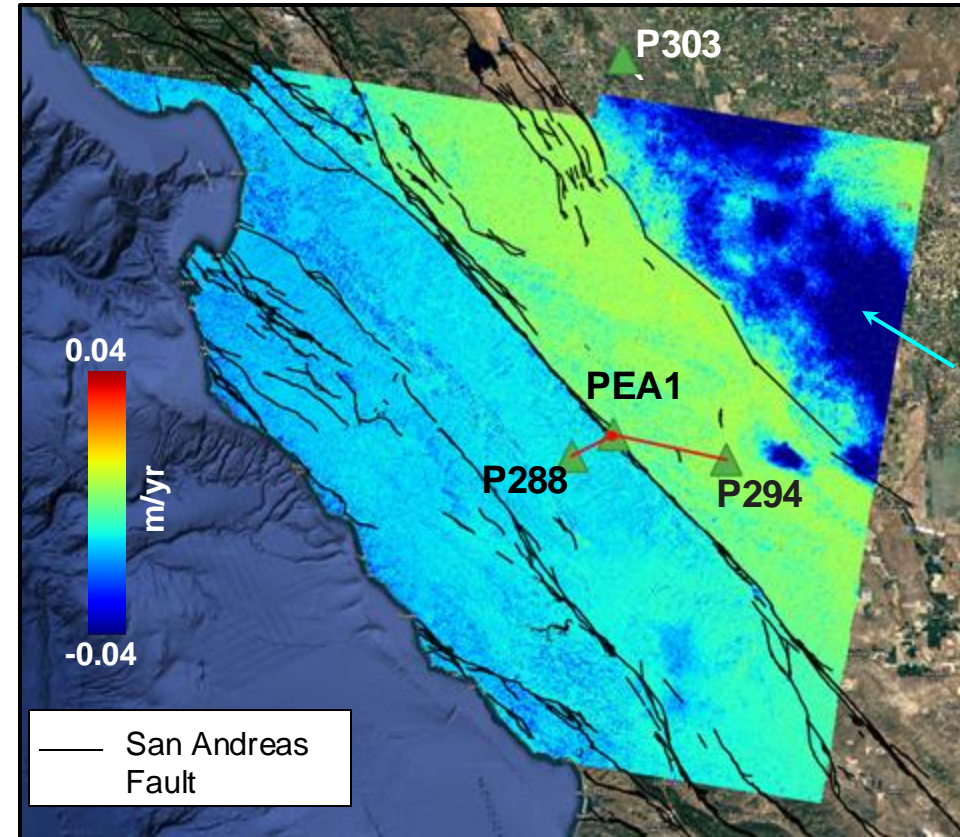
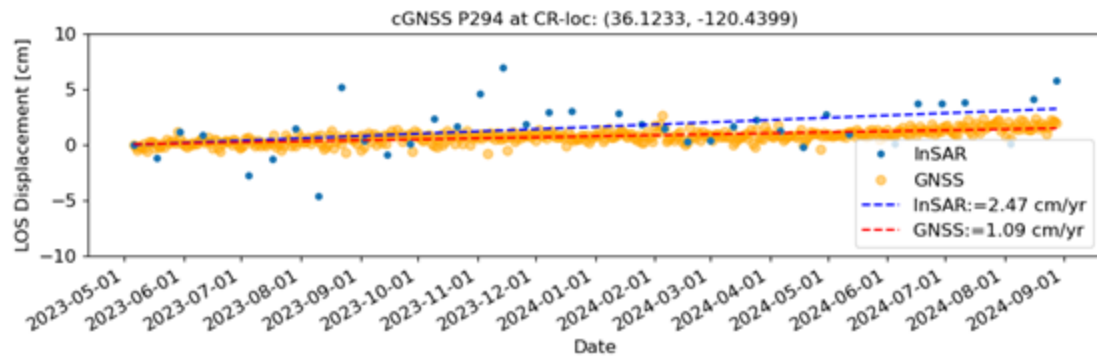
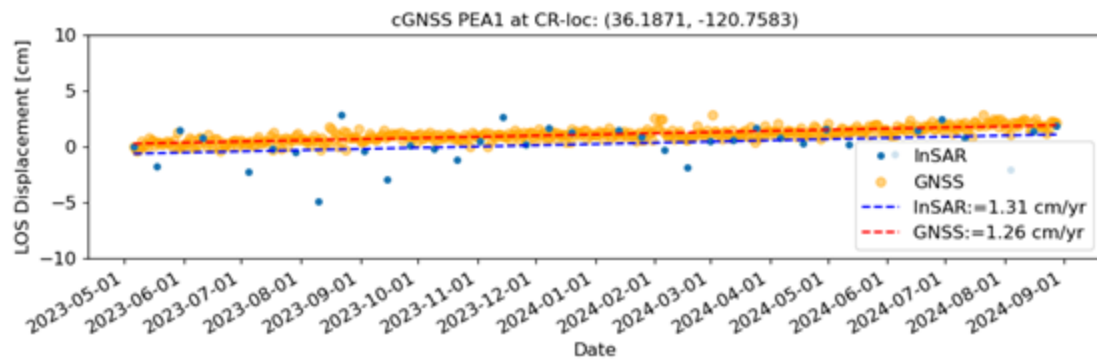
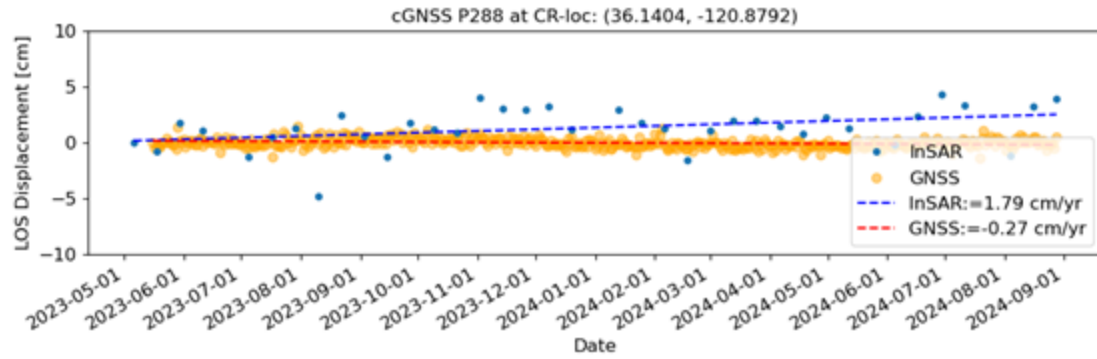
LOS Velocity DISP-  
S1 (m/yr)

Cross-section profile from P288 → PEA1 → P294



# Initial results:

## cGNSS vs DISP-S1 Timeseries at the CR-location



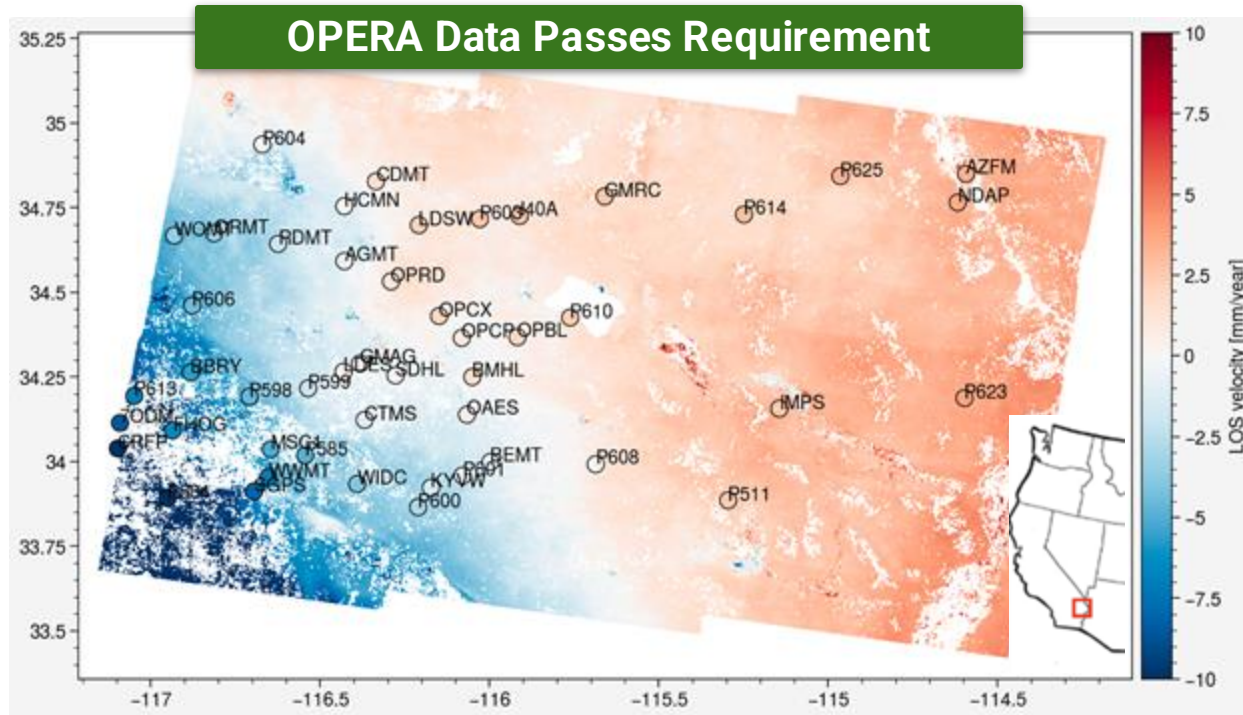
Central Valley subsidence

The larger scatter in the DISP-S1 timeseries can be related to tropospheric delay. We anticipate that this will improve with the addition of a tropospheric correction layer, soon to be provided by OPERA.

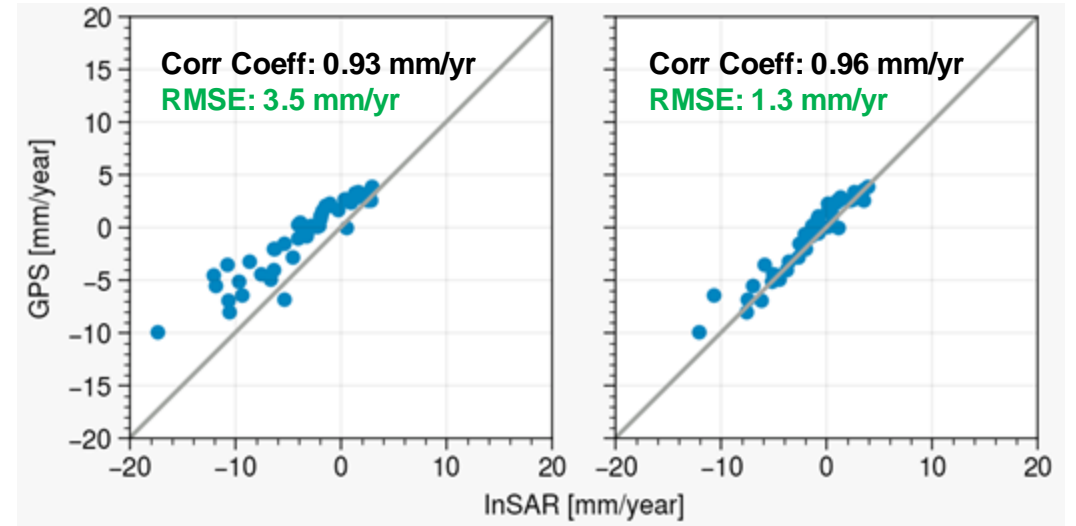
# Preliminary results: Mojave Validation site: Impact of Troposphere correction



## Velocity: Feb 2017 - Dec 2020



Without tropospheric  
delay correction



With tropospheric delay  
correction

Shows *improved* accuracy with application of correction layer for troposphere delay

# Global SAR-agnostic tropospheric correction ancillary

National Aeronautics and  
Space Administration



## NEW OPERA PRODUCT\*

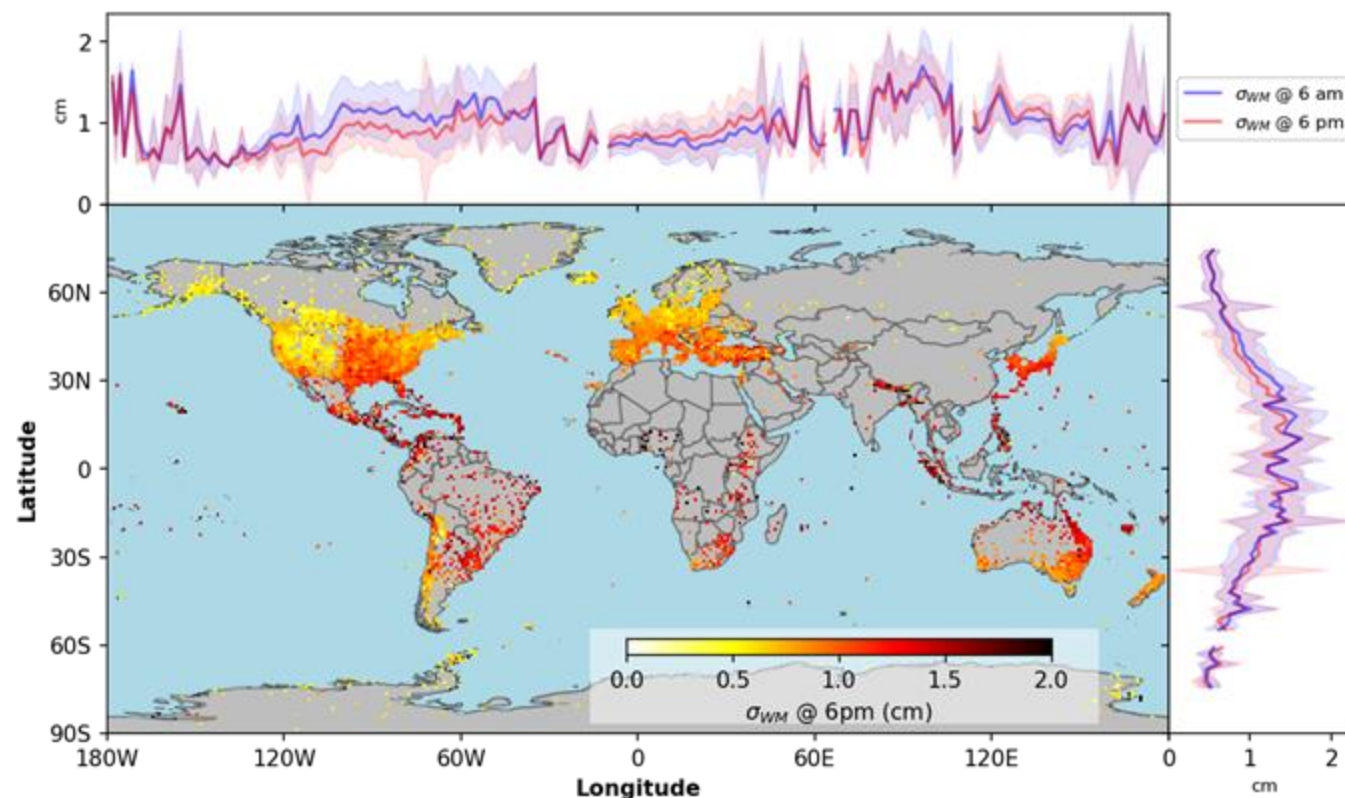
OPERA will create a global tropospheric correction ancillary to the DISP product:

- Derived from ECMWF HRES (~9km @ 00-06-12-18 UTC)
- 3D cube (x,y,z) allows for data compression (adopting NISAR idea)
- Zenith delays for SAR agnostic

**Distributed through ASF DAAC**

Currently starting from 2016

Release planned for mid 2025



HRES weather model performance against GNSS global Zenith tropospheric delay estimates (Bekaert et al., in prep)

# Open Source Validation Tools Available via GitHub

National Aeronautics and  
Space Administration



```
Workflow to Validate OPERA DISP-S1 Displacement Requirement

• Core modules follow the Notebooks for NISAR Solid Earth Algorithm Theoretical Basis Document developed by the NISAR Solid Earth Science Team; see https://github.com/nisar-solid/ATBD

# Parameters for papers!!!

### Choose a site from the 'sites' dictionary found 2 cells down
site = 'F08882'
work_dir = '/u/operapst/bato/work/CALVAL/disp-s1_official/v0.6/F08882/'
mintpy_dir = 'mintpy_output' # location of mintpy files
output_dir = 'results' # location to store output figures and text files
vmin = -15 # vmin/vmax for plotting
vmax = 15

calval_sites_csv = '/u/trappist-r8/bato/tools/c...'

# Mask file used for validation
maskfile = 'maskSpatialCoh.N5' # mask temporal

# Define spatial coherence threshold (necessary
coherenceBased_parm = 'yes'
minCoherence_parm = '0.3'
minTempCoherence_parm = '0.5'

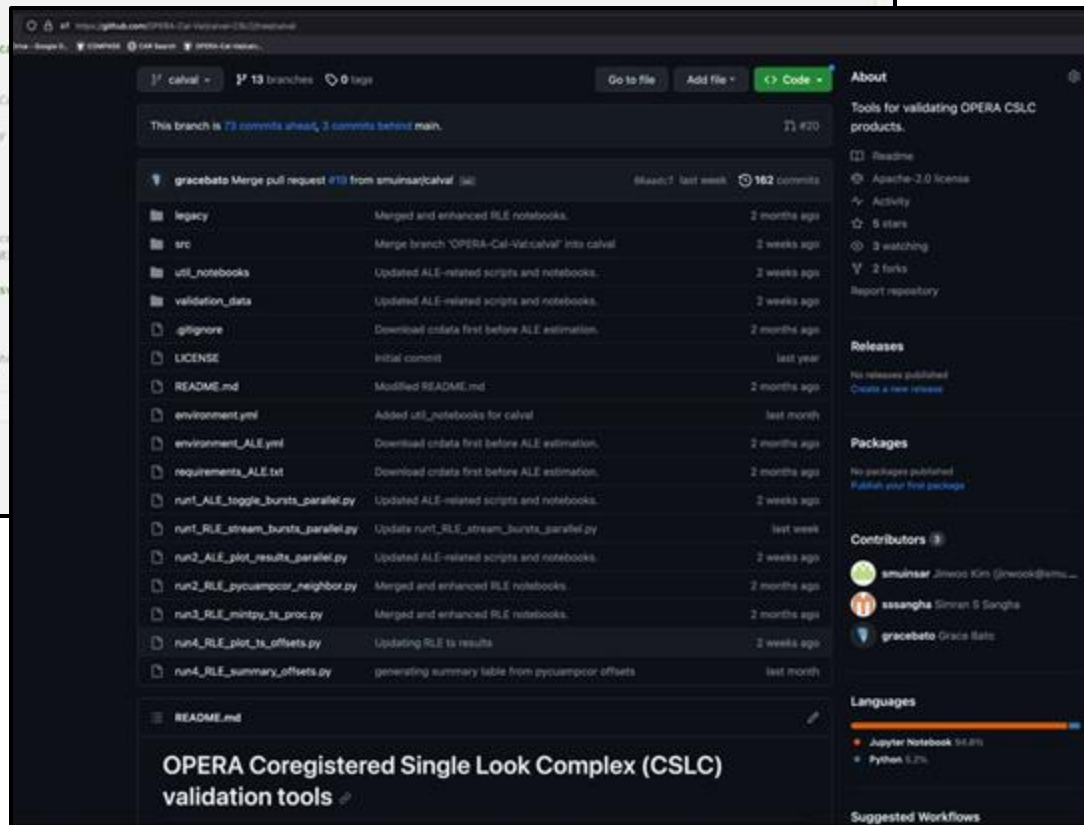
#set GASS Parameters
gps_completeness_threshold = 0.9 #0.9 #perc
gps_residual_stddev_threshold = 10. #0.01 #m

gnss_csv = 'gnss_select_station_list(site).csv'

#variability score threshold
apply_nonlinear_mask = True
thr_var_score = 0.6 # variability score th

[1] ✓ 0.0s × parameters + Tag

# load packages
import os
from datetime import datetime as dt
from pathlib import Path
import math
```



All the validation tools developed for OPERA CSLC-S1 and DISP-S1 (and others) are available on GitHub:

<https://github.com/OPERA-Cal-Val>

# Conclusion



- OPERA CSLC-S1 meets all L2 requirements. Production is ongoing.

	L2 Accuracy Requirements	CSLC-S1
ALE	1.5 m in Ground Range and Azimuth for 80% of validation data	100% of validation data met requirement
RLE	0.5 m in Ground Range and 0.75 m in Azimuth for 80% of validation data	88% of validation data met requirement

- OPERA is on track to start DISP-S1 production on December 2024.

# Backup

National Aeronautics and  
Space Administration

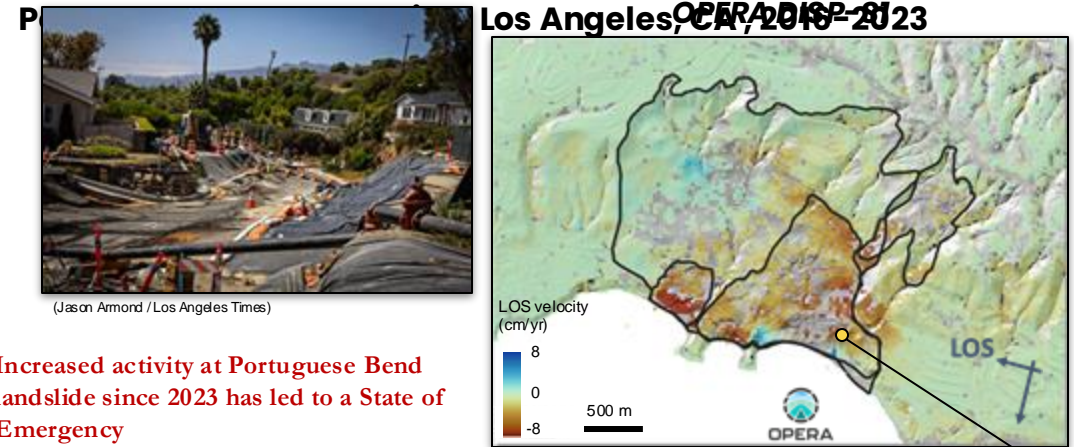




# Exciting Applications!



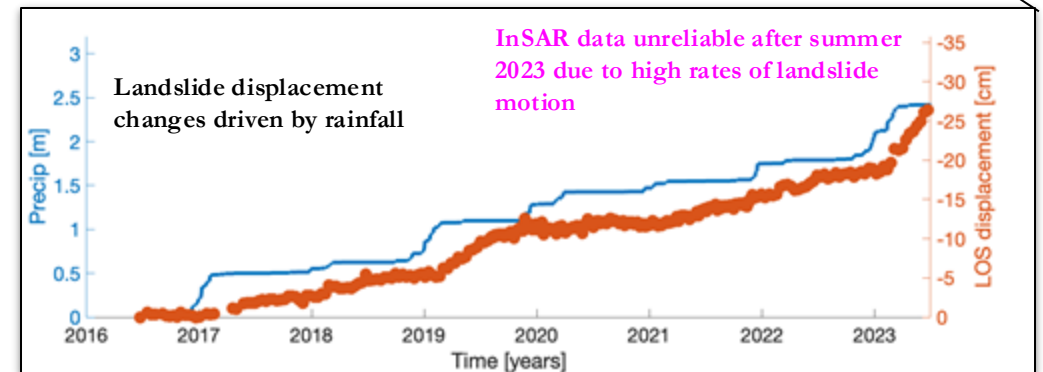
- Example: OPERA's DISP product will be extremely valuable for monitoring active landslides.
  - The Portuguese Bend landslide which started to accelerate significantly in summer 2023, and continues to move at high rates today. The resulting destruction of homes and infrastructure has prompted Gov. Newsom to declare a State emergency.



Increased activity at Portuguese Bend landslide since 2023 has led to a State of Emergency

**Eos**  
**Rancho Palos Verdes Landslides Have Residents Seeking Science**  
*Residents of Rancho Palos Verdes are looking to the scientific community for help in understanding the slow-moving landslides that are destroying their community.*  
*A project [OPERA] led by NASA's Jet Propulsion Laboratory will produce a data set [OPERA DISP] of land surface displacements across North America that will be useful for Rancho Palos Verdes city officials [and residents]*

OPERA DISP-SI Time series



Prelim. OPERA DISP-SI data provided by S. Staniewicz (OPERA - JPL). Rainfall data from PRISM

# OPERA Coregistered SLC (CSLC-S1): General Information



The North America-scope CSLC-S1 datasets are *burst-wise*, geocoded to the same geographical grid and result in aligned time-series of SLC images.

The product includes:

- Complex backscatter (HDF5)
  - Co-polarization (VV or HH) for Sentinel-1

`OPERA_L2_CSLC-S1_T064-135523-IW2_20230625T015058Z_20230907T122709Z_S1A_VV_v0.2.h5`

- Geometric data layers
  - Distributed in a separate HDF5 file (STATIC LAYER)

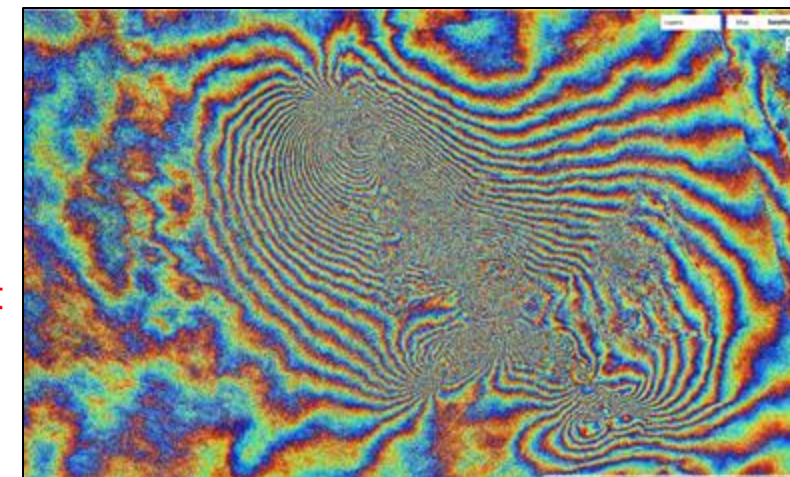
`OPERA_L2_CSLC-S1-STATIC_T064-135523-IW2_20140403_20230903T090947Z_S1A_v0.2.h5`

- CSLC-S1 products are corrected for:

- 1) bistatic delay
- 2) azimuth FM rate mismatch
- 3) Doppler induced range shift
- 4) range shift due to Solid Earth tides
- 5) range delay due to troposphere (static model)
- 6) range delay due to ionosphere

} SAR processing related

} Earth environment related



Wrapped phase (merged bursts). Ridgecrest, CA.

**The CSLC products allow for direct interferogram generation.**